

# Multiscale Convergence Properties for Spectral Approximations of a Model Kinetic Equation

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September 26, 2019

# Acknowledgements

- Collaborator:

- ▶ Cory Hauck (ORNL / UTK)

- Sponsor:

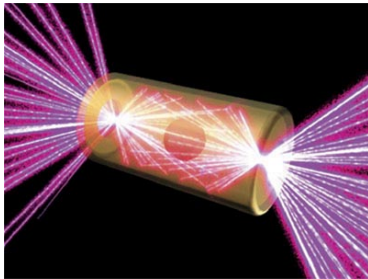
- ▶ US Department of Energy, Applied Math Program

# Outline

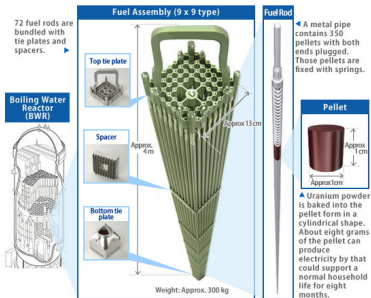
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- 3 Theoretical results: isotropic i.c.
- 4 Benefits from  $P_N$  to  $P_{N+1}$
- 5 Results: anisotropic i.c.
- 6 Summary

# Introduction

# Problem Setting



(a) Visualization of a Hohlraum



(b) Assembly for a Boiling Water Reactor

- Particles passing through a static material medium are **absorbed**, **scattered**, or **emitted** by the material.
- Particles are characterized by a **kinetic density**  $f(x, E, \Omega, t)$  where
  - ▶  $x \in X \subset \mathbb{R}^3$  is the particle **position**
  - ▶  $E \in (0, \infty)$  is the particle **energy**
  - ▶  $\Omega \in \mathbb{S}^2$  is the particle **direction** of flight
  - ▶  $t \geq 0$  is **time**

# Linear Transport Equation

- Cauchy problem for the **kinetic density**  $f(x, \Omega, t)$ :

$$\left\{ \begin{array}{l} \partial_t f + \underbrace{\Omega \cdot \nabla_x f}_{\text{advection}} + \underbrace{\overbrace{\sigma_a f}^{\text{absorption}} + \overbrace{\sigma_s (f - \bar{f})}^{\text{scattering}}}_{\text{interactions}} = \underbrace{q}_{\text{source}} \\ f(x, \Omega, 0) = g(x, \Omega) \end{array} \right.$$

- ▶ Mono-energetic particles with speed **1** (**single group**, so independent of  $E$ )
- ▶ domain:  $x \in \mathbb{R}^3$ ,  $\Omega \in \mathbb{S}^2$ ,  $t \in [0, \infty)$
- ▶ cross-sections:  $\sigma_a$  and  $\sigma_s$  are absorption and scattering cross-sections
- ▶ angular average:  $\bar{f} = \frac{1}{4\pi} \int_{\mathbb{S}^2} f(x, \Omega, t) d\Omega$
- ▶ source (emitting particles):  $q$

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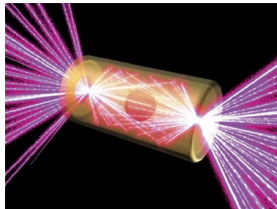
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  - ▶ source (emitting particles):  $q$
- Assumptions: static material, isotropic scattering, no absorption ( $\sigma_a = 0$ ) and no source ( $q = 0$ )

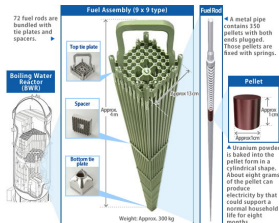
$$\partial_t f + \Omega \cdot \nabla_x f + \sigma_s (f - \bar{f}) = 0$$

# Applications

- Photons (fusion reactors, radiation in clouds, radiotherapy)
- Neutrinos (core-collapse supernova)
- Neutrons (fission reactors, imaging and scattering experiments)
- Electron transport in materials (semi-conductors, radiotherapy)
- Plasma simulations (fusion, plasma switches, space weather)



Visualization of a Hohlraum



Assembly for a Boiling Water Reactor



# Numerical Challenges

- High dimensional space:  $x \in \mathbb{R}^3$ ,  $\Omega \in \mathbb{S}^2$ , 5D
- Coupling to the medium: nonlinearity, e.g.  $\sigma_s(f)$ .
- **Multiscale dynamics**: diffusive, streaming, and transition regimes
  - ▶ Diffusive scaling
    - ★ "strong scattering":  $\sigma_s \rightarrow \epsilon^{-1} \sigma_s$
    - ★ "long-time dynamics":  $t \rightarrow \epsilon^{-1} t$
  - ▶ Scaled equation (WLOG,  $\sigma_s = 1$ )

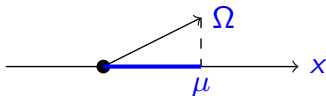
$$\epsilon \partial_t f + \Omega \cdot \nabla_x f + \frac{1}{\epsilon} (f - \bar{f}) = 0$$

# Transport in 1-D

- Slab transport: the kinetic density  $f(x, \mu, t)$  is the solution to

$$\epsilon \partial_t f + \mu \partial_x f + \frac{1}{\epsilon} (f - \bar{f}) = 0 \quad (1)$$

- ▶  $x \in [-\pi, \pi)$ : scalar coordinate along the axis perpendicular to a material slab; add periodic boundary condition
- ▶  $\mu \in [-1, 1]$ : the cosine of the angle between the  $x$ -axis and the direction of particle travel
- ▶  $\bar{f} = \frac{1}{2} \int_{-1}^1 f d\mu$ : angular average
- ▶  $\epsilon > 0$ : a scaling parameter measuring the relative strength of different processes
- ▶ initial condition  $f(x, \mu, 0) = g(x, \mu)$



# Transport in 1-D

- Slab transport:

$$\epsilon \partial_t f + \mu \partial_x f + \frac{1}{\epsilon} (f - \bar{f}) = 0 \quad (1)$$

- Denote the evolution operator as

$$\mathcal{T}: f \mapsto - \left( \mu \partial_x f + \frac{1}{\epsilon} (f - \bar{f}) \right)$$

then (1) becomes

$$\epsilon \partial_t f = \mathcal{T} f.$$

# Spectral Approximation (Angular Discretization)

- Spectral approximation on  $\mu$ : collision  $\rightarrow$  smoothness
- Legendre expansion for  $f$  in  $\mu$ :

$$f(x, \mu, t) = \sum_{\ell=0}^{\infty} f_{\ell}(x, t) p_{\ell}(\mu), \quad f_{\ell}(x, t) = \int_{-1}^1 p_{\ell}(\mu) f(x, \mu, t) d\mu,$$

where  $p_{\ell}(\mu)$  are the normalized Legendre polynomials, which satisfy

$$\mu p_{\ell} = a_{\ell} p_{\ell+1} + a_{\ell-1} p_{\ell-1}.$$

- The coefficients/moments  $f_{\ell}$  correspond to the physical quantities.

# Spectral Approximation (Angular Discretization)

- slab transport:

$$\epsilon \partial_t f + \mu \partial_x f + \frac{1}{\epsilon} (f - \bar{f}) = 0$$

- Moment equations (infinite system):

$$\begin{cases} \epsilon \partial_t f_0 + a_0 \partial_x f_1 = 0, & l = 0; \\ \epsilon \partial_t f_l + a_l \partial_x f_{l+1} + a_{l-1} \partial_x f_{l-1} + \frac{1}{\epsilon} f_l = 0, & l \geq 1. \end{cases}$$

- $P_N$  equations (closure of moments):

$$\begin{cases} \epsilon \partial_t f_0^N + a_0 \partial_x f_1^N = 0, & l = 0; \\ \epsilon \partial_t f_l^N + a_l \partial_x f_{l+1}^N + a_{l-1} \partial_x f_{l-1}^N + \frac{1}{\epsilon} f_l^N = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t f_N^N + a_{N-1} \partial_x f_{N-1}^N + \frac{1}{\epsilon} f_N^N = 0, & l = N. \end{cases}$$

# Motivation

# Diffusion Limit

- Diffusion Approximation: in diffusive regimes (high scattering  $\epsilon \ll 1$ )

$$f = \rho + \mathcal{O}(\epsilon), \quad \rho = \frac{1}{2} \int_{-1}^1 f(x, \mu) d\mu$$

$$\partial_t \rho - \partial_x \left( \frac{1}{3} \partial_x \rho \right) = 0$$

- Formal results based on Hilbert expansion:
  - ▶ Larsen and Keller 1974
  - ▶ Habetler and Matkowsky 1975
- Rigorous analysis
  - ▶ Blankenship and Papanicolaou 1978
  - ▶ Bardos, Santos and Sentis 1984
- Cheap
- Inaccurate in non-diffusive regimes

# Transition Regimes

- $0 < \epsilon < 1$ , but not  $\epsilon \ll 1$



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$$\|f(\cdot, \cdot, t) - f^N(\cdot, \cdot, t)\|_{L^2(dx d\mu)} \leq \frac{C(t)}{N^q}.$$

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- Question: A good  $\epsilon$  dependent estimate?

Guess: for  $0 < \epsilon < 1$ ,

$$e^N = f - f^N = \mathcal{O}(\epsilon^{N+1}).$$

# Errors of $P_N$ methods

$$e^N := f - f^N = \eta + \xi$$

- Consistency error

$$\eta := f - \mathcal{P}(f) = \sum_{\ell=N+1}^{\infty} f_{\ell}(x, t) p_{\ell}(\mu)$$

- Stability error

$$\xi := \mathcal{P}(f) - f^N = \sum_{\ell=0}^N \xi_{\ell}(x, t) p_{\ell}(\mu)$$

with moment error

$$\xi_{\ell} = f_{\ell} - f_{\ell}^N.$$

# Numerical Observation

Example: Consider

$$\begin{cases} \epsilon \partial_t f + \mu \partial_x f + \frac{1}{\epsilon} f = \frac{1}{\epsilon} \bar{f}, t \in (0, 1], \\ f(0, x, \mu) = g^{(i)}(x, \mu), \end{cases}$$

for  $[x, \mu] \in [-\pi, \pi) \times [-1, 1]$ , with periodic boundary condition and three different initial conditions:

$$g^{(1)} = (1 + \mu - \mu^2) \left( 1 + 1_{[-\frac{\pi}{2}, \frac{\pi}{2}]}(x) \right),$$

$$g^{(2)} = (1 + \mu - \mu^2) \left( 1 + \cos x \cdot 1_{[-\frac{\pi}{2}, \frac{\pi}{2}]}(x) \right),$$

$$g^{(3)} = (1 + \mu - \mu^2) (1 + \cos x).$$

$\epsilon$	$g^{(1)}$									
	$f_0^N$	order	$f_1^N$	order	$f_2^N$	order	$f_3^N$	order	$f_4^N$	order
1/2	1.45E+00		1.01E-01		3.16E-02		1.36E-02		1.15E-02	
1/8	1.44E+00	0.00	2.22E-02	1.09	1.47E-03	2.21	1.10E-04	3.47	1.34E-05	4.87
1/32	1.44E+00	0.00	5.50E-03	1.01	9.06E-05	2.01	1.66E-06	3.02	4.74E-08	4.07
1/128	1.44E+00	0.00	1.37E-03	1.00	5.66E-06	2.00	2.59E-08	3.00	1.84E-10	4.00
1/512	1.44E+00	0.00	3.44E-04	1.00	3.54E-07	2.00	4.05E-10	3.00	7.18E-13	4.00

$\epsilon$	$g^{(2)}$									
	$f_0^N$	order	$f_1^N$	order	$f_2^N$	order	$f_3^N$	order	$f_4^N$	order
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1/8	1.27E+00	0.00	1.83E-02	1.12	1.34E-03	2.20	1.17E-04	3.20	1.27E-05	4.36
1/32	1.27E+00	0.00	4.52E-03	1.01	8.21E-05	2.01	1.77E-06	3.02	4.70E-08	4.04
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**Table:** Convergence rate of the coefficients  $f_\ell^N$  in  $L^2$  norm for  $P_4$  method at  $t = 1$ .

$$f_\ell \sim f_\ell^N = \mathcal{O}(\epsilon^\ell), \quad \ell = 0, 1, \dots, N.$$

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$$f_\ell \sim f_\ell^N = \mathcal{O}(\epsilon^\ell), \quad \ell = 0, 1, \dots, N.$$

- $\eta = \mathcal{O}(\epsilon^{N+1})$ . This is expected.
- What about  $\xi$ ? And  $e^N$ ?



$\epsilon$	$P_1$ error		$P_2$ error		$P_3$ error		$P_4$ error		$P_5$ error	
	order	$1 + 1 = 2$	order	$2 + 1 = 3$	order	$3 + 1 = 4$	order	$4 + 1 = 5$	order	$5 + 1 = 6$
1/2		5.62E-02		3.00E-02		1.86E-02		1.37E-02		1.09E-02
1/8		2.05E-03	2.39	1.18E-04	4.00	1.35E-05	5.21	2.34E-06	6.26	4.42E-07
1/32		1.26E-04	2.01	1.67E-06	3.07	4.74E-08	4.08	2.00E-09	5.10	9.30E-11
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1/8		1.96E-03	2.14	1.20E-04	3.39	1.27E-05	4.45	1.54E-06	5.53	1.97E-07
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1/128		1.08E-05	2.00	3.44E-08	3.00	1.36E-10	4.00	5.32E-13	5.00	2.09E-15
1/512		6.78E-07	2.00	5.38E-10	3.00	5.30E-13	4.00	5.20E-16	5.00	5.09E-19 <sup>1</sup>

**Table:** Convergence rate of the  $L^2$  error for  $P_1$  to  $P_5$  methods (compared with as a reference solution from  $P_{65}$ ) at  $t = 1$ .

$$e^N = f - f^N = \mathcal{O}(\epsilon^{N+1})$$

<sup>1</sup>Multiprecision Computing Toolbox for MATLAB by Advanpix LLC. with 250 digits is used.

$\epsilon$	$\xi_0^N$		$\xi_1^N$		$\xi_2^N$		$\xi_3^N$		$\xi_4^N$	
	order		order		order		order		order	
1/2	5.48E-03		3.36E-03		4.63E-03		4.02E-03		5.79E-03	
1/8	5.30E-08	8.33	1.08E-08	9.12	1.85E-08	8.96	8.13E-08	7.80	4.26E-07	6.86
1/32	7.16E-13	8.09	3.44E-14	9.13	2.14E-13	8.20	4.41E-12	7.09	9.30E-11	6.08
1/128	1.08E-17	8.01	1.30E-19	9.01	3.21E-18	8.01	2.67E-16	7.01	2.25E-14	6.01
1/512	1.65E-22	8.00	4.95E-25	9.00	4.89E-23	8.00	1.63E-20	7.00	5.50E-18	6.00

$\epsilon$	$\xi_0^N$		$\xi_1^N$		$\xi_2^N$		$\xi_3^N$		$\xi_4^N$	
	order		order		order		order		order	
1/2	7.92E-04		4.15E-04		7.04E-04		7.69E-04		1.24E-03	
1/8	1.76E-08	7.73	4.01E-09	8.33	5.46E-09	8.49	2.66E-08	7.41	1.93E-07	6.32
1/32	2.24E-13	8.13	1.28E-14	9.13	6.00E-14	8.24	1.50E-12	7.06	4.44E-11	6.05
1/128	3.38E-18	8.01	4.82E-20	9.01	8.97E-19	8.01	9.11E-17	7.00	1.08E-14	6.00
1/512	5.15E-23	8.00	1.84E-25	9.00	1.37E-23	8.00	5.56E-21	7.00	2.63E-18	6.00

$\epsilon$	$\xi_0^N$		$\xi_1^N$		$\xi_2^N$		$\xi_3^N$		$\xi_4^N$	
	order		order		order		order		order	
1/2	2.81E-07		1.11E-06		7.75E-06		4.68E-05		2.41E-04	
1/8	1.01E-10	5.72	2.26E-12	9.46	1.43E-10	7.86	2.25E-09	7.17	3.56E-08	6.36
1/32	1.59E-15	7.97	5.94E-18	9.27	2.14E-15	8.01	1.35E-13	7.01	8.57E-12	6.01
1/128	2.43E-20	8.00	2.20E-23	9.02	3.26E-20	8.00	8.23E-18	7.00	2.09E-15	6.00
1/512	3.71E-25	8.00	8.36E-29	9.00	4.97E-25	8.00	5.02E-22	7.00	5.10E-19	6.00

**Table:** Convergence rate of the  $L^2$  error  $\xi_\ell^N$  of the coefficients  $f_\ell^N$  for  $P_4$  method at  $t = 1$ .

$$\xi_\ell^N := f_\ell - f_\ell^N = \begin{cases} \mathcal{O}(\epsilon^{2N}) & \ell = 0; \\ \mathcal{O}(\epsilon^{2N+2-\ell}), & \ell = 1, \dots, N. \end{cases}$$

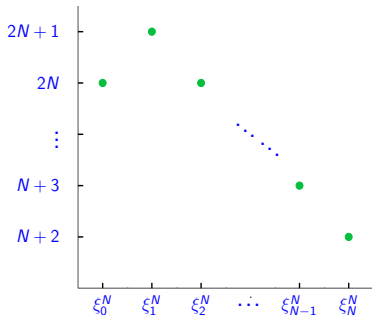
- Formal  $\xi_1^N = \mathcal{O}(\epsilon^{2N+1})$  [Larsen, Morel and McGhee 1996]
- Formal  $\xi_\ell^N = \mathcal{O}(\epsilon^{2N+2-\ell})$  for  $\ell \geq 1$  [Hauck and Lowrie 2009]

# Observations

For all three initial conditions,

1.  $e^N = \mathcal{O}(\epsilon^{N+1})$
2. a)  $\xi_0^N = \mathcal{O}(\epsilon^{2N})$   
b) other  $\xi_\ell^N = \mathcal{O}(\epsilon^{2N+2-\ell}) \implies$
3.  $f_\ell^N = \mathcal{O}(\epsilon^\ell)$

Super convergence is important, because the low order moments correspond to the important physical quantities.



Theoretical results: isotropic i.c.

# Theoretical results (isotropic i.c.)

## Theorem (Multiscale convergence)

Given isotropic initial condition  $g \in H^1(dx)$ , there exists an absolute constant  $\lambda_1$  s.t.

$$\|f - f^N\|_{L^2(dx d\mu)}(t) \leq B(g)e^{-\frac{\lambda_1 t}{\epsilon^2}} + C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + D(g, N, t)\epsilon^{N+1},$$

Moreover,

$$\|f_\ell - f_\ell^N\|_{L^2(dx)}(t) \leq \begin{cases} C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + E(g, N, 2, t)\epsilon^{2N}, & \ell = 0 \\ C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + E(g, N, \ell, t)\epsilon^{2N+2-\ell}, & 1 \leq \ell \leq N. \end{cases}$$

Notice,  $\lambda_1 = \frac{1}{45}$ ;  $D(g, N, t)$  and  $E(g, N, \ell, t)$  are positive and bounded for any  $t > 0$ , and exponentially decreasing w.r.t  $t$  for  $t$  big enough. <sup>2</sup>

---

<sup>2</sup>Chen, Z., & Hauck, C. (2019). "Multiscale convergence properties for spectral approximations of a model kinetic equation." *Mathematics of Computation*, 88(319), 2257-2293.

# Errors of $P_N$ methods

$$e^N := f - f^N = \eta + \xi$$

- Consistency error

$$\eta := f - \mathcal{P}(f) = \sum_{\ell=N+1}^{\infty} f_{\ell}(x, t) p_{\ell}(\mu)$$

- Stability error

$$\xi := \mathcal{P}(f) - f^N = \sum_{\ell=0}^N \xi_{\ell}(x, t) p_{\ell}(\mu)$$

with moment error

$$\xi_{\ell} = f_{\ell} - f_{\ell}^N.$$

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The equation for  $\xi$  is

$$\epsilon \partial_t \xi = \mathcal{P} \mathcal{T} \xi - a_N p_N \partial_x f_{N+1}.$$

# Asymptotic estimates on $f_\ell$

## Lemma

Given isotropic initial condition  $g \in L^2(dx)$ , the coefficients  $f_\ell(t, x)$  of the solution  $f^N$  to the  $P_N$  equations satisfy

$$\|f_\ell\|_{L^2(dx)}(t) \leq B(g)e^{-\frac{\lambda_1 t}{\epsilon^2}} + C(g, \ell, t) \epsilon^\ell, \quad \ell \geq 0.$$

Notice,  $\lambda_1 = \frac{1}{45}$ ;  $C(g, \ell, t)$  is bounded for any  $t > 0$  and is monotonically decreasing w.r.t.  $t$ .



# Some ideas

- Energy dissipation (periodic b.c.)

$$\partial_t \sum_{\ell=0}^{\infty} |f_{\ell}|^2 = -\frac{2}{\epsilon^2} \sum_{\ell=1}^{\infty} |f_{\ell}|^2 \leq 0$$

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$$\epsilon \partial_t f_{\ell} + a_{\ell} \partial_x f_{\ell+1} + a_{\ell-1} \partial_x f_{\ell-1} + \frac{1}{\epsilon} f_{\ell} = 0$$

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- Fourier Analysis:  $\partial_x \rightarrow ik$ , and then for  $(\ell, k)$ -spectral coefficients,

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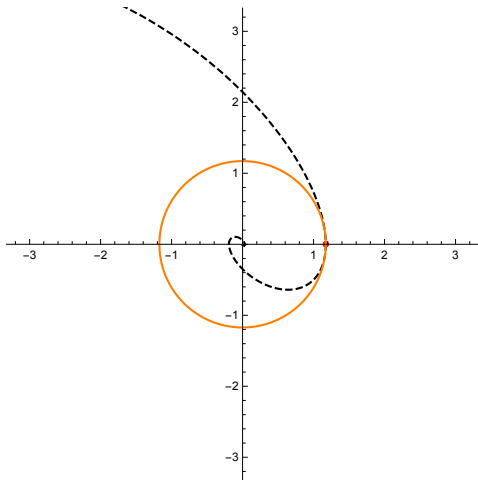
$$\partial_t \sum_{\ell=0}^{\infty} |f_{\ell,k}|^2 = -\frac{2}{\epsilon^2} \sum_{\ell=1}^{\infty} |f_{\ell,k}|^2,$$

$$\epsilon \partial_t f_{\ell,k} + a_\ell i k f_{\ell+1,k} + a_{\ell-1} i k f_{\ell-1,k} + \frac{1}{\epsilon} f_{\ell,k} = 0.$$

Separate frequencies to control the growth rates mode by mode, and then sum up over frequencies  $k$ .

# Hypo-coercivity

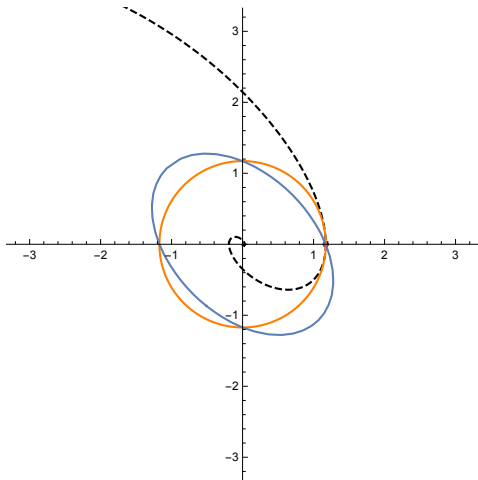
- Prof. David Levermore points out the hypo-coercivity.
- [Dolbeault, Mouhot and Schmeiser 2015] the exponential rate of convergence to the equilibrium (unscaled linear kinetic equations)
- Example:  $P_1$  with  $k = 1$ :





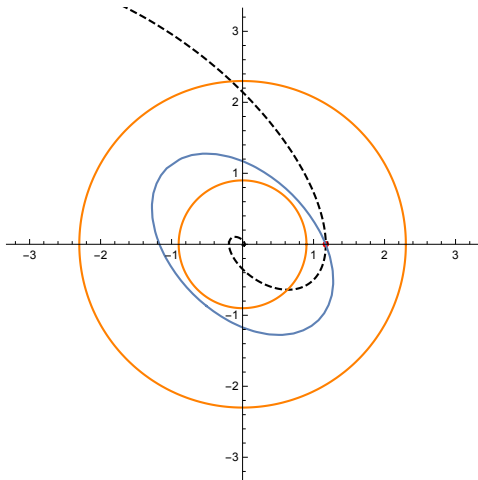
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# Hypoocoercivity

- Rewrite energy dissipation as

$$\partial_t H_0^k(f) = -\frac{2}{\epsilon^2} H_1^k(f).$$

$$H_j^k(u) := \frac{1}{2} \sum_{\ell=j}^{\infty} |u_{\ell,k}|^2$$

# Hypocoercivity

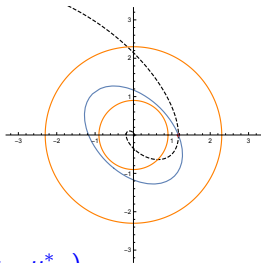
- Rewrite energy dissipation as

$$\partial_t H_0^k(f) = -\frac{2}{\epsilon^2} H_1^k(f).$$

- The modified energy is

$$(H_0^k + h_\gamma^k)(u) \quad \text{and} \quad h_\gamma^k(u) = -\frac{\gamma}{4a_0} \text{Im}(u_{0,k} u_{1,k}^*)$$

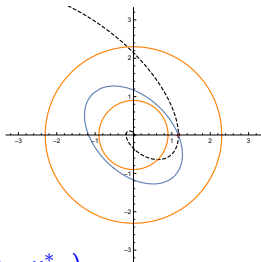
is a real-valued compensating function



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is a real-valued compensating function satisfying

- equivalence

$$\left(1 - \frac{\gamma}{2}\right) H_0^k(u) \leq (H_0^k + h_\gamma^k)(u) \leq \left(1 + \frac{\gamma}{2}\right) H_0^k(u);$$

- time derivative

$$\partial_t h_\gamma^k(u) \leq \gamma \left( \underbrace{-\frac{k}{16\epsilon} |u_{0,k}|^2}_{\text{"magic"}} + \underbrace{\left(\frac{k}{4\epsilon} + \frac{3}{8\epsilon^3 k}\right) |u_{1,k}|^2 + \frac{k}{5\epsilon} |u_{2,k}|^2}_{\text{"trade-off"}} \right).$$

# Initial estimates on $f_\ell$

- Method of modified energy (MME): ( $u \leftarrow f$ )

$$\partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) \leq -\frac{2}{\epsilon^2} H_3^k(f) - \sum_{\ell=0}^2 c_{\gamma,\ell} |f_{\ell,k}|^2$$

where

$$c_{\gamma,0} = \frac{\gamma k}{16\epsilon}, \quad c_{\gamma,1} = \frac{1}{\epsilon^2} - \frac{\gamma k}{4\epsilon} - \frac{3\gamma}{8\epsilon^3 k}, \quad c_{\gamma,2} = \frac{1}{\epsilon^2} - \frac{\gamma k}{5\epsilon}.$$

For each  $k$ , choose suitable  $\gamma$ , and find positive lower bounds on  $\{c_{\gamma,i}\}_{i=0}^2$ .

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---

- (i) **High frequency:** ( $k\epsilon > 1/2$ )

$$\gamma := \gamma^{\text{high}} \simeq \frac{1}{k\epsilon}$$

$$H_0^k(f)(t) < 6H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$$

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**(ii) Low frequency:** ( $0 < k\epsilon \leq \frac{1}{2}$ )

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# Initial estimates on $f_\ell$

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$$H_0^k(f) := \frac{1}{2} \sum_{\ell=0}^{\infty} |f_{\ell,k}|^2$$

↓

$f_{\ell,k}$

↓ sum over  $k$

$f_\ell$

# Initial estimates on $f_\ell$

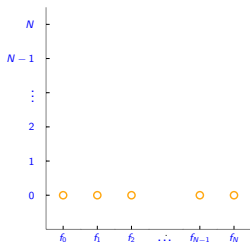
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Initial estimate:

$$\|f_\ell\|_{L^2(dx)}^2(t) \leq 12 \overbrace{\sum_{|k|\epsilon > 1/2} H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}}^{\text{high frequencies}} + \underbrace{C(g, 0, t)^2}_{\text{low frequencies}}$$

with

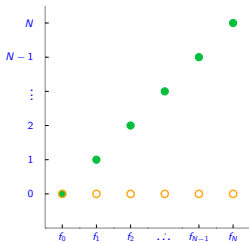
$$C(g, 0, t) = \left[ 24 \max_{k>0} H_0^k(g) \sum_{k>0} e^{-2\lambda_2 k^2 t} \right]^{\frac{1}{2}}.$$

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- Next goal:  $f_\ell$  is bounded by a finer estimate:

$$\|f_\ell\|_{L^2(dx)}^2(t) \leq 12 \sum_{|k| \epsilon > 1/2} \overbrace{H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}}^{\text{high frequencies}} + \underbrace{C(g, \ell, t)^2 \epsilon^{2\ell}}_{\text{low frequencies}}$$

with

$$C(g, \ell, t) = \left[ 24 \max_{k>0} H_0^k(g) \sum_{k>0} (Ak)^{2\ell} e^{-2\lambda_2 k^2 t} \right]^{\frac{1}{2}}.$$

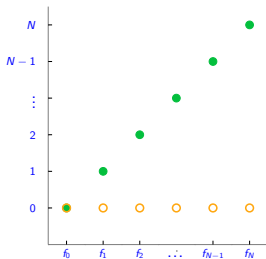
# Zoom-in estimates on $f_\ell$

- Moment equations

$$\begin{cases} \epsilon \partial_t f_{0,k} + a_0 i k f_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t f_{\ell,k} + a_\ell i k f_{\ell+1,k} + a_{\ell-1} i k f_{\ell-1,k} + \frac{1}{\epsilon} f_{\ell,k} = 0, & \ell \geq 1. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

(0) For  $n \geq 0$ ,  $|f_{n,k}|(t) \leq C_0^k \epsilon^0 k^0 e^{-\lambda_2 k^2 t}$ .



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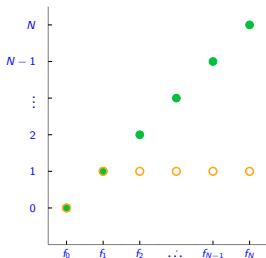
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(1) For  $n \geq 1$ ,

$$\begin{aligned} \partial_t |f_{n,k}| + \frac{1}{\epsilon^2} |f_{n,k}| &\leq \frac{k}{\epsilon} (a_n |f_{n+1,k}| + a_{n-1} |f_{n-1,k}|) \\ &\leq \frac{2k}{\sqrt{3}\epsilon} \left( C_0^k \epsilon^0 k^0 e^{-\lambda_2 k^2 t} \right). \end{aligned}$$

$$\begin{aligned} |f_{n,k}|(t) &\leq e^{-\frac{t}{\epsilon^2}} \overset{0}{g_{n,k}} + \frac{2k}{\sqrt{3}\epsilon} \int_0^t e^{-\frac{t-s}{\epsilon^2}} \left( C_0^k \epsilon^0 k^0 e^{-\lambda_2 k^2 s} \right) ds \\ &\leq C_{0+1}^k \epsilon^{0+1} k^{0+1} e^{-\lambda_2 k^2 t} \end{aligned}$$



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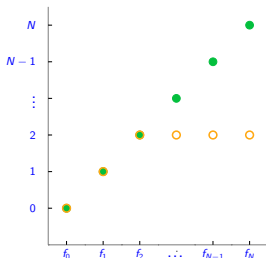
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(1) For  $n \geq 1$ ,  $|f_{n,k}|(t) \leq C_1^k \epsilon^1 k^1 e^{-\lambda_2 k^2 t}$ .

(2) For  $n \geq 2$ ,

$$\begin{aligned} \partial_t |f_{n,k}| + \frac{1}{\epsilon^2} |f_{n,k}| &\leq \frac{k}{\epsilon} (a_n |f_{n+1,k}| + a_{n-1} |f_{n-1,k}|) \\ &\leq \frac{2k}{\sqrt{3}\epsilon} \left( C_1^k \epsilon^1 k^1 e^{-\lambda_2 k^2 t} \right). \end{aligned}$$

$$\begin{aligned} |f_{n,k}|(t) &\leq e^{-\frac{t}{\epsilon^2}} \overset{0}{g_{n,k}} + \frac{2k}{\sqrt{3}\epsilon} \int_0^t e^{-\frac{t-s}{\epsilon^2}} \left( C_1^k \epsilon^1 k^1 e^{-\lambda_2 k^2 s} \right) ds \\ &\leq C_{1+1}^k \epsilon^{1+1} k^{1+1} e^{-\lambda_2 k^2 t} \end{aligned}$$



# Zoom-in estimates on $f_\ell$

- Moment equations

$$\begin{cases} \epsilon \partial_t f_{0,k} + a_0 i k f_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t f_{\ell,k} + a_\ell i k f_{\ell+1,k} + a_{\ell-1} i k f_{\ell-1,k} + \frac{1}{\epsilon} f_{\ell,k} = 0, & \ell \geq 1. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

(0) For  $n \geq 0$ ,  $|f_{n,k}|(t) \leq C_0^k \epsilon^0 k^0 e^{-\lambda_2 k^2 t}$ .

(1) For  $n \geq 1$ ,  $|f_{n,k}|(t) \leq C_1^k \epsilon^1 k^1 e^{-\lambda_2 k^2 t}$ .

(2) For  $n \geq 2$ ,  $|f_{n,k}|(t) \leq C_2^k \epsilon^2 k^2 e^{-\lambda_2 k^2 t}$ .



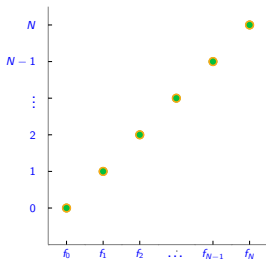
Method of induction

( $\ell$ ) For  $n \geq \ell$ ,  $|f_{n,k}|(t) \leq C_\ell^k \epsilon^\ell k^\ell e^{-\lambda_2 k^2 t}$ .



Take finest  $\epsilon$ -estimate

For any  $\ell \geq 0$ ,  $|f_{\ell,k}|(t) \leq C_\ell^k \epsilon^\ell \underbrace{k^\ell e^{-\lambda_2 k^2 t}}_{\text{summable over } k}$ .



# Zoom-in estimates

- Moment equations

$$\begin{cases} \epsilon \partial_t f_{0,k} + a_0 i k f_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t f_{\ell,k} + a_\ell i k f_{\ell+1,k} + a_{\ell-1} i k f_{\ell-1,k} + \frac{1}{\epsilon} f_{\ell,k} = 0, & \ell \geq 1. \end{cases}$$

- 1  $k = 0$  terms:  $f_{0,0}(t) = f_{0,0}(0)$ ,  $\epsilon \partial_t f_{\ell,0} + \frac{1}{\epsilon} f_{\ell,0} = 0$  for  $\ell \geq 1$
- 2 High frequency terms,  $|k|\epsilon > \frac{1}{2}$ : decay exponentially  $\mathcal{O}(e^{-\frac{\lambda_1 t}{\epsilon^2}})$
- 3 Low frequency terms,  $0 < |k|\epsilon \leq \frac{1}{2}$ :  $f_{\ell,k}$  behaves like  $\mathcal{O}(\epsilon^\ell)$

## Lemma (Asymptotic approximation)

Given isotropic initial condition  $g \in L^2(dx)$ , the coefficients  $f_\ell(t, x)$  of the solution  $f^N$  to the  $P_N$  equations satisfy

$$\|f_\ell\|_{L^2(dx)}(t) \leq B(g) e^{-\frac{\lambda_1 t}{\epsilon^2}} + C(g, \ell, t) \epsilon^\ell, \quad \ell \geq 0.$$



# Consistency error

$$\|\eta\|_{L^2(d\mu dx)}^2(t) = \sum_{\ell=N+1}^{\infty} \|f_{\ell}\|_{L^2(dx)}^2(t)$$

## Lemma

Given isotropic initial condition  $g \in L^2(dx)$ ,

$$\|\eta\|_{L^2(d\mu dx)}(t) \leq B(g)e^{-\frac{\lambda_1 t}{\epsilon^2}} + \sqrt{3}C(g, N+1, t)\epsilon^{N+1}.$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_\ell i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_\ell i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_\gamma^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2$$

- Remark 1:**

$$\partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) \leq -\frac{2}{\epsilon^2} H_3^k(f) - \sum_{\ell=0}^2 c_{\gamma,\ell} |f_{\ell,k}|^2$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_\ell i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_\gamma^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2$$

- Remark 1:

$$\partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) \leq -\frac{2}{\epsilon^2} H_3^k(f) - \sum_{\ell=0}^2 c_{\gamma,\ell} |f_{\ell,k}|^2$$

- Remark 2:

$$\xi(0) = 0$$

- Remark 3:

$$\|f_{N+1}\| = \mathcal{O}(\epsilon^{N+1})$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_{\ell} i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_{\gamma}^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2,$$

- (i) **High frequency:** With estimate on source of the error coefficient system

$$|f_{N+1,k}|^2(t) \leq 12 H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$$

$$\xrightarrow{\text{MME}} H_0^k(\xi)(t) \leq 6t k^2 H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}} = 6t H_0^k(\partial_x g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}.$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_{\ell} i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_{\gamma}^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2,$$

- (ii) **Low frequency:** With estimate on source of the error coefficient system

$$|f_{N+1,k}|(t) \leq C_{N+1}^k \epsilon^{N+1} k^{N+1} e^{-\lambda_2 k^2 t}$$

$$\xrightarrow{\text{MME}} H_0^k(\xi)(t) \leq \frac{t}{2} (C_{N+1}^k)^2 k^{2(N+2)} e^{-2\lambda_2 k^2 t} \epsilon^{2(N+1)}.$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_{\ell} i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_{\gamma}^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2,$$

- (i) **High frequency:**  $H_0^k(\xi)(t) \leq 6t H_0^k(\partial_x g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$   
 (ii) **Low frequency:**  $H_0^k(\xi)(t) \leq \frac{t}{2} [C_{N+1}^k]^2 k^{2(N+2)} e^{-2\lambda_2 k^2 t} \epsilon^{2(N+1)}$

## Lemma

Given isotropic initial condition  $g \in H^1(dx)$ ,

$$\|\xi\|_{L^2(d\mu dx)}(t) \leq C(\partial_x g) \sqrt{t} e^{-\frac{\lambda_1 t}{\epsilon^2}} + \frac{\sqrt{t}}{A} C(g, N+2, t) \epsilon^{N+1}.$$

## $P_N$ error

$$\|\eta\|_{L^2(d\mu dx)}(t) \leq B(g)e^{-\frac{\lambda_1 t}{\epsilon^2}} + \sqrt{3}C(g, N+1, t)\epsilon^{N+1}.$$

+

$$\|\xi\|_{L^2(d\mu dx)}(t) \leq C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + \frac{\sqrt{t}}{A}C(g, N+2, t)\epsilon^{N+1}.$$

↓

$$\|e^N\|_{L^2(dx d\mu)}(t) \leq \left( B(g) + C(\partial_x g)\sqrt{t} \right) e^{-\frac{\lambda_1 t}{\epsilon^2}} + D(g, N, t)\epsilon^{N+1},$$



# $P_N$ error

$$\|\eta\|_{L^2(d\mu dx)}(t) \leq B(g)e^{-\frac{\lambda_1 t}{\epsilon^2}} + \sqrt{3}C(g, N+1, t)\epsilon^{N+1}.$$

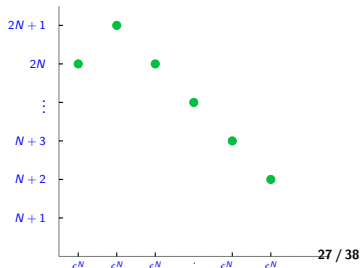
+

$$\|\xi\|_{L^2(d\mu dx)}(t) \leq C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + \frac{\sqrt{t}}{A}C(g, N+2, t)\epsilon^{N+1}.$$

↓

$$\|e^N\|_{L^2(dx d\mu)}(t) \leq \left( B(g) + C(\partial_x g)\sqrt{t} \right) e^{-\frac{\lambda_1 t}{\epsilon^2}} + D(g, N, t)\epsilon^{N+1},$$

**Next:** moment errors  $\xi_\ell = f_\ell - f_\ell^N$   
with more tricky "Zoom-in" techniques



# Moment errors

Error equations:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

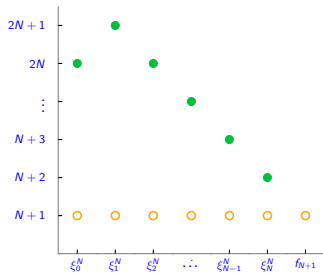
For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

The previous result

$$H_0^k(\xi)(t) \leq \frac{t}{2} [C_{N+1}^k]^2 k^{2(N+2)} e^{-2\lambda_2 k^2 t} \epsilon^{2(N+1)}$$

yields, for  $0 \leq n \leq N$ ,

$$|\xi_{l,k}|(t) \lesssim \epsilon^{N+1} k^{N+2} e^{-\lambda_2 k^2 t}$$



# Moment errors

Error equations:

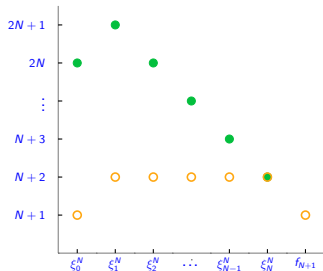
$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

For  $1 \leq n \leq N$ ,

$$\begin{aligned} & \partial_t |\xi_{n,k}| + \frac{1}{\epsilon^2} |\xi_{n,k}| \\ & \leq \frac{k}{\epsilon} (a_{n-1} |\xi_{n-1,k}| + (1 - \delta_{n,N}) a_n |\xi_{n+1,k}| + \delta_{n,N} a_N |f_{N+1,k}|) \\ & \lesssim \epsilon^N k^{N+3} e^{-\lambda_2 k^2 t} \end{aligned}$$

$$\xrightarrow{\text{integrate over time}} |\xi_{n,k}|(t) \lesssim \epsilon^{N+2} k^{N+3} e^{-\lambda_2 k^2 t}$$



# Moment errors

Error equations:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

Consider

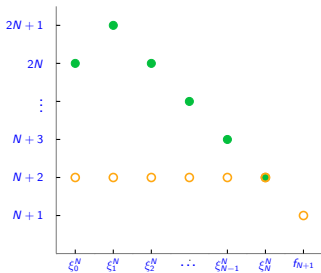
- smaller system  $\{\xi_{n,k}\}_{n=0}^{N-1}$
- source term  $\xi_{N,k}$

Using MME gives, for  $0 \leq n \leq N-1$ ,

$$|\xi_{n,k}|(t) \lesssim \epsilon^{N+2} k^{N+4} e^{-\lambda_2 k^2 t}$$

In particular,

$$|\xi_{0,k}|(t) \lesssim \epsilon^{N+2} k^{N+4} e^{-\lambda_2 k^2 t}$$



# Moment errors

Error equations:

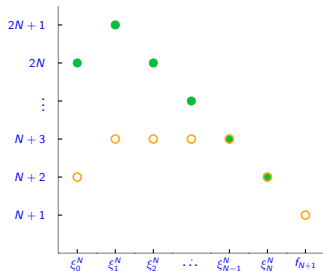
$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

For  $1 \leq n \leq N-1$ ,

$$\begin{aligned} & \partial_t |\xi_{n,k}| + \frac{1}{\epsilon^2} |\xi_{n,k}| \\ & \leq \frac{k}{\epsilon} (a_{n-1} |\xi_{n-1,k}| + (1 - \delta_{n,N}) a_n |\xi_{n+1,k}| + \delta_{n,N} a_N |f_{N+1,k}|) \\ & \lesssim \epsilon^{N+1} k^{N+5} e^{-\lambda_2 k^2 t} \end{aligned}$$

$$\xrightarrow{\text{integrate over time}} |\xi_{n,k}|(t) \lesssim \epsilon^{N+3} k^{N+5} e^{-\lambda_2 k^2 t}$$



# Moment errors

Error equations:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

Consider

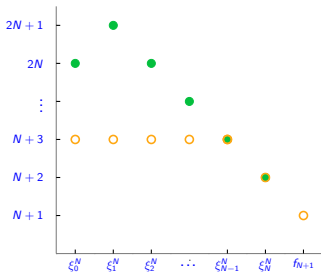
- smaller system  $\{\xi_{n,k}\}_{n=0}^{N-2}$
- source term  $\xi_{N-1,k}$

Using MME gives, for  $0 \leq n \leq N-2$ ,

$$|\xi_{n,k}|(t) \lesssim \epsilon^{N+3} k^{N+6} e^{-\lambda_2 k^2 t}$$

In particular,

$$|\xi_{0,k}|(t) \lesssim \epsilon^{N+3} k^{N+6} e^{-\lambda_2 k^2 t}$$



# Moment errors

Error equations:

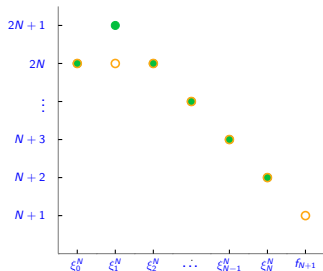
$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

---

For  $0 \leq n \leq 2$ ,

$$|\xi_{n,k}| \lesssim \epsilon^{2N} k^{3N} e^{-\lambda_2 k^2 t}$$



# Moment errors

Error equations:

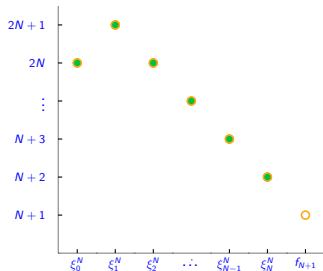
$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

For low frequency terms ( $0 < |k|\epsilon \leq \frac{1}{2}$ ): "Zoom-in procedure"

For  $n = 1$ ,

$$\begin{aligned} & \partial_t |\xi_{n,k}| + \frac{1}{\epsilon^2} |\xi_{n,k}| \\ & \leq \frac{k}{\epsilon} (a_{n-1} |\xi_{n-1,k}| + (1 - \delta_{n,N}) a_n |\xi_{n+1,k}| + \delta_{n,N} a_N |f_{N+1,k}|) \\ & \lesssim \epsilon^{2N-1} k^{3N+1} e^{-\lambda_2 k^2 t} \end{aligned}$$

$$\xrightarrow{\text{integrate over time}} |\xi_{1,k}|(t) \lesssim \epsilon^{2N+1} k^{3N+1} e^{-\lambda_2 k^2 t}$$





# Moment errors

- Error equations:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_l i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{cases}$$

- 1  $k = 0$  terms:  $\xi_{\ell,0} = 0$  for  $0 \leq \ell \leq N$
- 2 High frequency terms: decay exponentially  $\mathcal{O}(e^{-\frac{\lambda_1 t}{\epsilon^2}})$
- 3 Low frequency terms: **method of induction** + **MME**  
 $\xi_{0,k} \sim \mathcal{O}(\epsilon^{2N}), \xi_{\ell,k} \sim \mathcal{O}(\epsilon^{2N+2-\ell})$

## Theorem (Superconvergence in moments)

Given  $g \in H^1(dx)$ , there exists an absolute constant  $\lambda_1$  s.t.

$$\|\xi_\ell\|_{L^2(dx)}(t) \leq \begin{cases} C(\partial_x g) \sqrt{t} e^{-\frac{\lambda_1 t}{\epsilon^2}} + E(g, N, 2, t) \epsilon^{2N}, & l = 0 \\ C(\partial_x g) \sqrt{t} e^{-\frac{\lambda_1 t}{\epsilon^2}} + E(g, N, l, t) \epsilon^{2N+2-\ell}, & 1 \leq l \leq N. \end{cases}$$

Benefits from  $P_N$  to  $P_{N+1}$

In main theorems,

$$\|e^N\|_{L^2(dx d\mu)}(t) \leq B(g)e^{-\frac{\lambda_1 t}{\epsilon^2}} + C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + D(g, N, t)\epsilon^{N+1}.$$

$$\|\xi_\ell^N\|_{L^2(dx)}(t) \leq \begin{cases} C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + E(g, N, 2, t)\epsilon^{2N}, & \ell = 0 \\ C(\partial_x g)\sqrt{t}e^{-\frac{\lambda_1 t}{\epsilon^2}} + E(g, N, \ell, t)\epsilon^{2N+2-\ell}, & 1 \leq \ell \leq N. \end{cases}$$

### Observation

1.  $e^N = \mathcal{O}(\epsilon^{N+1})$
2. a)  $\xi_0^N = \mathcal{O}(\epsilon^{2N})$   
 b) other  $\xi_\ell^N = \mathcal{O}(\epsilon^{2N+2-\ell})$

### Theory

1.  $e^N \leq D(g, N, t)\epsilon^{N+1}$
2. a)  $\xi_0^N \leq E(g, N, 2, t)\epsilon^{2N}$   
 b)  $\xi_\ell^N \leq E(g, N, \ell, t)\epsilon^{(2N+2-\ell)}$

Using the error estimates to indicate the benefit from  $P_N$  to  $P_{N+1}$ :

$$\frac{\|e^{N+1}\|}{\|e^N\|} \sim \frac{D(g, N+1, t)\epsilon^{N+2}}{D(g, N, t)\epsilon^{N+1}} = \frac{D(g, N+1, t)}{D(g, N, t)}\epsilon = \mathcal{O}(\epsilon),$$

if  $D(g, N, t)$  does NOT grow fast w.r.t.  $N$ . Similarly,

$$\frac{\|\xi_\ell^{N+1}\|}{\|\xi_\ell^N\|} \sim \frac{E(g, N+1, \ell, t)}{E(g, N, \ell, t)}\epsilon^2 = \mathcal{O}(\epsilon^2).$$

### Observation

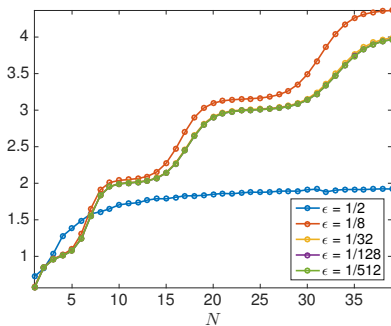
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### Theory

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# Benefits of increasing $N$ : $\|e^N\|_{L^2(d\mu dx)}$

$$\frac{\|e^{N+1}\|}{\|e^N\| \epsilon} < 5$$

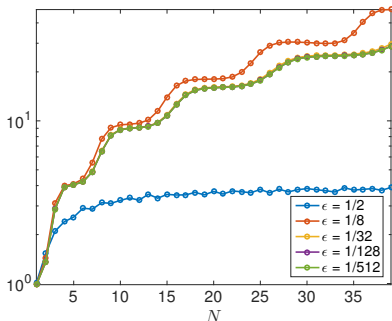


(a)  $\frac{\|e^{N+1}\|}{\|e^N\| \epsilon}$

Errors of  $P_N$  equations,  $N = 1, \dots, 40$ .

# Benefits of increasing N: $\|\xi_0^N\|_{L^2(dx)}$

$$\frac{\|\xi_0^{N+1}\|}{\|\xi_0^N\|\epsilon^2} < 50$$

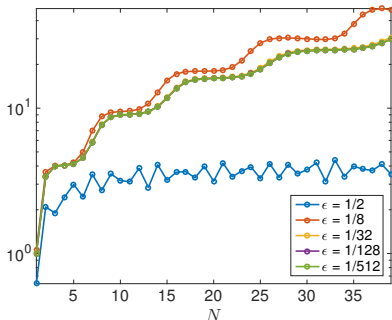


(a)  $\frac{\|\xi_0^{N+1}\|}{\|\xi_0^N\|\epsilon^2}$

Errors of  $f_0^N$  of  $P_N$  equations,  $N = 1, \dots, 40$ .

# Benefits of increasing N: $\|\xi_1^N\|_{L^2(dx)}$

$$\frac{\|\xi_1^{N+1}\|}{\|\xi_1^N\|\epsilon^2} < 50$$

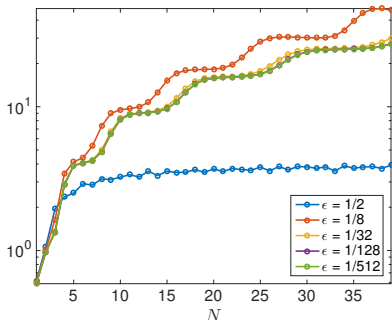


(a)  $\frac{\|\xi_1^{N+1}\|}{\|\xi_1^N\|\epsilon^2}$

Errors of  $f_1^N$  of  $P_N$  equations,  $N = 1, \dots, 40$ .

# Benefits of increasing N: $\|\xi_2^N\|_{L^2(dx)}$

$$\frac{\|\xi_2^{N+1}\|}{\|\xi_2^N\|\epsilon^2} < 50$$



(a)  $\frac{\|\xi_2^{N+1}\|}{\|\xi_2^N\|\epsilon^2}$

Errors of  $f_2^N$  of  $P_N$  equations,  $N = 1, \dots, 40$ .



# The sum of the series

All these constants in the estimates are multiples of the following sum

$$a_n(s) := \sum_{k>0} \left\{ k^{2n} e^{-k^2 s} \right\},$$

with some  $n$ ,  $s = 2\lambda_2 t$  and the constant  $\lambda_2$ , which has the same **step behavior** as in the previous numerical benefits, and has the same growth rate as function

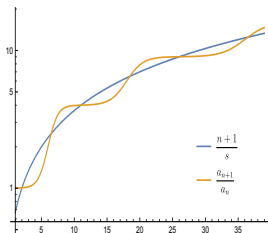
$$a_n(s) \sim \frac{n!}{s^n},$$

and

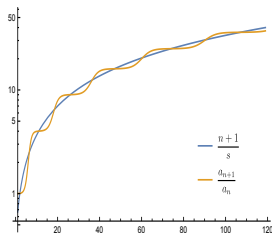
$$a_{n+1}(s)/a_n(s) \sim \frac{(n+1)!}{s^{n+1}} \bigg/ \frac{n!}{s^n} = \frac{n+1}{s}.$$

We also have some analytic results to support this numerical observation.

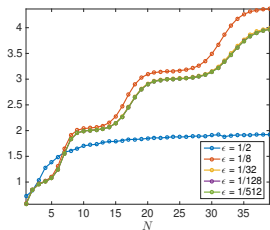
# The sum of the series



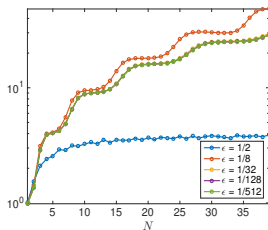
(a)  $a_{n+1}(1.3)/a_n(1.3), n \leq 40$



(b)  $a_{n+1}(1.3)/a_n(1.3), n \leq 120$



(c)  $\frac{\|e^{N+1}\|}{\|e^N\|_\epsilon} (1)$



(d)  $\frac{\|\xi_0^{N+1}\|}{\|\xi_0^N\|_\epsilon^2} (1)$

Results: anisotropic i.c.

# Numerical results

Super convergence properties relate to the highest non-zero moment of initial condition  $g$ . Consider

$$g(x, \mu) = \sum_{\ell=0}^{m_0} g_{\ell}(x) p_{\ell}(\mu).$$

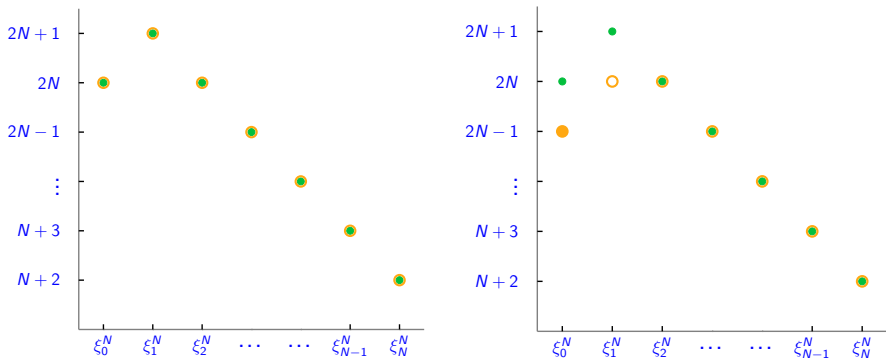
$m_0$	numerical	theoretical
$m_0 = 0, 1$	$\min\{2N + \ell, 2N + 2 - \ell\}$	$\min\{2N + \ell, 2N + 2 - \ell\}$
$2 \leq m_0 < N + 1$	$\min\{2N + 2 - m_0 + \ell, 2N + 2 - \ell\}$	$\min\{2N + 1 - m_0 + \ell, 2N + 2 - \ell\}$
$m_0 \geq N + 1$	$\min\{N + 1 + \ell, 2N + 2 - \ell\}$	$\min\{N + \ell, 2N + 2 - \ell\}$

**Table:** Numerical and theoretical orders of convergence rates for the  $\ell^{\text{th}}$  moment.

# Numerical results

$m_0$	numerical	theoretical
$m_0 = 0, 1$ $2 \leq m_0 < N + 1$ $m_0 \geq N + 1$	$\min\{2N + \ell, 2N + 2 - \ell\}$ $\min\{2N + 2 - m_0 + \ell, 2N + 2 - \ell\}$ $\min\{N + 1 + \ell, 2N + 2 - \ell\}$	$\min\{2N + \ell, 2N + 2 - \ell\}$ $\min\{2N + 1 - m_0 + \ell, 2N + 2 - \ell\}$ $\min\{N + \ell, 2N + 2 - \ell\}$

**Table:** Numerical and theoretical orders of convergence rates for the  $\ell^{\text{th}}$  moment.

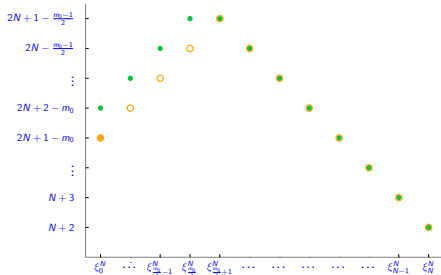
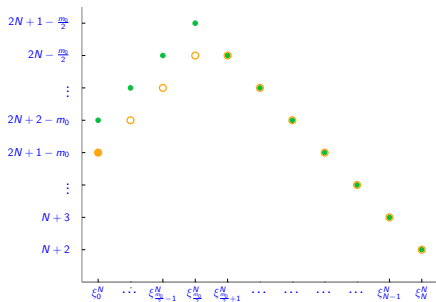


Left:  $m_0 = 0$  or  $1$ ; right:  $m_0 = 2$ .

# Numerical results

$m_0$	numerical	theoretical
$m_0 = 0, 1$ $2 \leq m_0 < N + 1$ $m_0 \geq N + 1$	$\min\{2N + \ell, 2N + 2 - \ell\}$ $\min\{2N + 2 - m_0 + \ell, 2N + 2 - \ell\}$ $\min\{N + 1 + \ell, 2N + 2 - \ell\}$	$\min\{2N + \ell, 2N + 2 - \ell\}$ $\min\{2N + 1 - m_0 + \ell, 2N + 2 - \ell\}$ $\min\{N + \ell, 2N + 2 - \ell\}$

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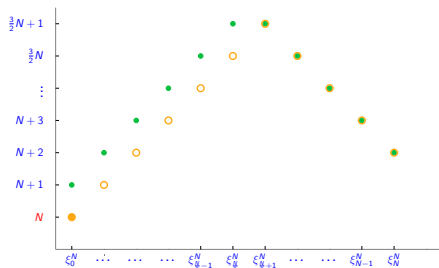
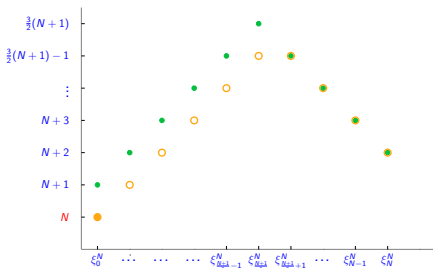


$2 \leq m_0 < N + 1$   
 Left:  $m_0$  even; right:  $m_0$  odd.

# Numerical results

$m_0$	numerical	theoretical
$m_0 = 0, 1$ $2 \leq m_0 < N + 1$ $m_0 \geq N + 1$	$\min\{2N + \ell, 2N + 2 - \ell\}$ $\min\{2N + 2 - m_0 + \ell, 2N + 2 - \ell\}$ $\min\{N + 1 + \ell, 2N + 2 - \ell\}$	$\min\{2N + \ell, 2N + 2 - \ell\}$ $\min\{2N + 1 - m_0 + \ell, 2N + 2 - \ell\}$ $\min\{N + \ell, 2N + 2 - \ell\}$

**Table:** Numerical and theoretical orders of convergence rates for the  $\ell^{\text{th}}$  moment.



$m_0 \geq N + 1$   
 Left:  $N$  odd; right:  $N$  even.

# Summary

- A multiscale convergence property for the error of  $P_N$  method, which is  $\mathcal{O}(\epsilon^{N+1})$ , for linear kinetic equations with isotropic scattering, no absorption, no source, and isotropic initial condition.
- Super-convergence rate in the spectral approximation for each moment with  $P_N$  method.
- Asymptotic estimates for moments, i.e.,  $f_\ell$  and  $f_\ell^N$  are  $\mathcal{O}(\epsilon^\ell)$ .
- Future work:
  - ▶ optimal convergence rate for cases with anisotropic initial conditions
  - ▶ realistic domain with boundary conditions
  - ▶ non-zero absorption and sources
  - ▶ spatially dependent scattering and anisotropic scattering
  - ▶ alternative angular discretizations and nonlinear systems
  - ▶ error estimate for multiscale hybrid methods





Backup slides

# Initial estimates on $f_\ell$

- Method of modified energy (MME): ( $u \leftarrow f$ )

$$\partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) \leq -\frac{2}{\epsilon^2} H_3^k(f) - \sum_{\ell=0}^2 c_{\gamma,\ell} |f_{\ell,k}|^2$$

where

$$c_{\gamma,0} = \frac{\gamma k}{16\epsilon}, \quad c_{\gamma,1} = \frac{1}{\epsilon^2} - \frac{\gamma k}{4\epsilon} - \frac{3\gamma}{8\epsilon^3 k}, \quad c_{\gamma,2} = \frac{1}{\epsilon^2} - \frac{\gamma k}{5\epsilon}.$$

For each  $k$ , choose suitable  $\gamma$ , and find positive lower bounds on  $\{c_{\gamma,i}\}_{i=0}^2$ .

# Initial estimates on $f_\ell$

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For each  $k$ , choose suitable  $\gamma$ , and find positive lower bounds on  $\{c_{\gamma,i}\}_{i=0}^2$ .

---

- (i) High frequency: ( $k\epsilon > 1/2$ )

$$\gamma := \gamma^{\text{high}} := \frac{16}{29} \frac{1}{k\epsilon} < \frac{32}{29}.$$

Then

$$\begin{aligned} \partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) &\leq -\frac{2\lambda_1}{\epsilon^2} \left( H_0^k(f) + h_\gamma^k(f) \right) \\ \xrightarrow{\text{integrate in time}} \left( H_0^k(f) + h_\gamma^k(f) \right) (t) &\leq e^{-\frac{2\lambda_1 t}{\epsilon^2}} \left( H_0^k(g) + h_\gamma^k(g) \right) \\ \xrightarrow{\text{equivalence}} H_0^k(f)(t) &< 6H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}. \end{aligned}$$

# Initial estimates on $f_\ell$

- Method of modified energy (MME): ( $u \Leftarrow f$ )

$$\partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) \leq -\frac{2}{\epsilon^2} H_3^k(f) - \sum_{\ell=0}^2 c_{\gamma,\ell} |f_{\ell,k}|^2$$

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For each  $k$ , choose suitable  $\gamma$ , and find positive lower bounds on  $\{c_{\gamma,i}\}_{i=0}^2$ .

---

- (ii) Low frequency: ( $0 < k\epsilon \leq \frac{1}{2}$ )

$$\gamma := \gamma^{\text{low}} := \frac{64}{29} k\epsilon \leq \frac{32}{29}.$$

Then

$$\begin{aligned} \partial_t \left( H_0^k(f) + h_\gamma^k(f) \right) &\leq -\frac{2\lambda_2}{45} k^2 \left( H_0^k(f) + h_\gamma^k(f) \right) \\ \xrightarrow{\text{integrate in time}} &\left( H_0^k(f) + h_\gamma^k(f) \right) (t) \leq e^{-2\lambda_2 k^2 t} \left( H_0^k(g) + h_\gamma^k(g) \right) \\ \xrightarrow{\text{equivalence}} &H_0^k(f)(t) < 6H_0^k(g) e^{-2\lambda_2 k^2 t}. \end{aligned}$$

# Initial estimates on $f_\ell$

- Method of modified energy (MME): ( $u \Leftarrow f$ )

- (i) High frequency: ( $k\epsilon > 1/2$ )

$$H_0^k(f)(t) < 6H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$$

- (ii) Low frequency: ( $0 < k\epsilon \leq \frac{1}{2}$ )

$$H_0^k(f)(t) < 6H_0^k(g) e^{-2\lambda_2 k^2 t}$$

$$H_0^k(f) := \frac{1}{2} \sum_{\ell=0}^{\infty} |f_{\ell,k}|^2$$

↓

$f_{\ell,k}$

↓ sum over  $k$

$f_\ell$

# Initial estimates on $f_\ell$

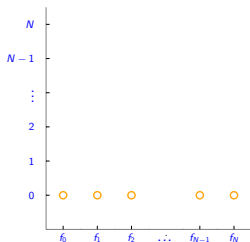
- Method of modified energy (MME): ( $u \leftarrow f$ )

- (i) High frequency: ( $k\epsilon > 1/2$ )

$$H_0^k(f)(t) < 6H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$$

- (ii) Low frequency: ( $0 < k\epsilon \leq \frac{1}{2}$ )

$$H_0^k(f)(t) < 6H_0^k(g) e^{-2\lambda_2 k^2 t}$$



Initial estimate:

$$\|f_\ell\|_{L^2(dx)}^2(t) \leq 12 \overbrace{\sum_{|k|\epsilon > 1/2} H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}}^{\text{high frequencies}} + \underbrace{C(g, 0, t)^2}_{\text{low frequencies}}$$

with

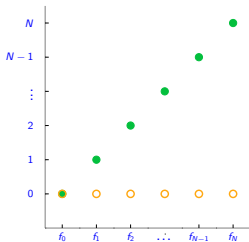
$$C(g, 0, t) = \left[ 24 \max_{k>0} H_0^k(g) \sum_{k>0} e^{-2\lambda_2 k^2 t} \right]^{\frac{1}{2}}.$$

# Initial estimates on $f_\ell$

- Method of modified energy (MME): ( $u \leftarrow f$ )

Initial estimate:

$$\|f_\ell\|_{L^2(dx)}^2(t) \leq 12 \sum_{|k| \epsilon > 1/2} H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}} + C(g, 0, t)^2$$



- Next goal:  $f_\ell$  is bounded by a finer estimate:

$$\|f_\ell\|_{L^2(dx)}^2(t) \leq 12 \sum_{|k| \epsilon > 1/2} \overbrace{H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}}^{\text{high frequencies}} + \underbrace{C(g, \ell, t)^2 \epsilon^{2\ell}}_{\text{low frequencies}}$$

with

$$C(g, \ell, t) = \left[ 24 \max_{k>0} H_0^k(g) \sum_{k>0} (Ak)^{2\ell} e^{-2\lambda_2 k^2 t} \right]^{\frac{1}{2}}.$$



# Stability error

- Stability error equation:

$$\left\{ \begin{array}{ll} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & l = 0; \\ \epsilon \partial_t \xi_{l,k} + a_l i k \xi_{l+1,k} + a_{l-1} i k \xi_{l-1,k} + \frac{1}{\epsilon} \xi_{l,k} = 0, & 1 \leq l \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & l = N. \end{array} \right.$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_{\ell} i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\begin{aligned} \partial_t \sum_{\ell=0}^N |\xi_{\ell,k}|^2 + \frac{2}{\epsilon^2} \sum_{\ell=1}^N |\xi_{\ell,k}|^2 &\leq \frac{a_N |k|}{\epsilon} |\xi_{N,k}| |f_{N+1,k}| \\ &\leq \frac{1}{2\epsilon^2} |\xi_{N,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2 \end{aligned}$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_{\ell} i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \sum_{\ell=0}^N |\xi_{\ell,k}|^2 + \frac{2}{\epsilon^2} \sum_{\ell=1}^N |\xi_{\ell,k}|^2 \leq \frac{a_N |k|}{\epsilon} |\xi_{N,k}| |f_{N+1,k}| \leq \frac{1}{2\epsilon^2} |\xi_{N,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2$$

$$\begin{aligned} \partial_t \left( H_0^k(\xi) + h_{\gamma}^k(\xi) \right) &\leq -\frac{2}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{1}{\epsilon^2} \frac{1}{2} |\xi_{N,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2 \\ &\leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2, \end{aligned}$$

- for  $f$ :

$$\partial_t \left( H_0^k(f) + h_{\gamma}^k(f) \right) \leq -\frac{2}{\epsilon^2} H_3^k(f) - \sum_{\ell=0}^2 c_{\gamma,\ell} |f_{\ell,k}|^2$$

- $\xi_{\ell,k}(0) = 0$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_\ell i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_\gamma^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2,$$

- (i) **High frequency:** With estimate on source of the error coefficient system

$$\frac{k^2}{6} |f_{N+1,k}|^2(t) \leq 2k^2 H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$$

$$\begin{aligned} \xrightarrow{\text{MME}} H_0^k(\xi)(t) &\leq 6t k^2 H_0^k(g) e^{-\frac{2\lambda_1 t}{\epsilon^2}} \\ &= 6t H_0^k(\partial_x g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}. \end{aligned}$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_\ell i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_\gamma^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2,$$

- (ii) **Low frequency:** With estimate on source of the error coefficient system

$$|f_{N+1,k}|(t) \leq C_{N+1}^k \epsilon^{N+1} k^{N+1} e^{-\lambda_2 k^2 t}$$

$$\begin{aligned} \xrightarrow{\text{MME}} \quad \left( H_0^k(\xi) + h_\gamma^k(\xi) \right) (t) &\leq \frac{k^2}{6} e^{-2\lambda_2 k^2 t} \int_0^t e^{2\lambda_2 k^2 s} |f_{N+1,k}|^2 ds \\ &\leq \frac{t}{6} (C_{N+1}^k)^2 k^{2(N+2)} e^{-2\lambda_2 k^2 t} \epsilon^{2(N+1)}. \end{aligned}$$

# Stability error

- Stability error equation:

$$\begin{cases} \epsilon \partial_t \xi_{0,k} + a_0 i k \xi_{1,k} = 0, & \ell = 0; \\ \epsilon \partial_t \xi_{\ell,k} + a_{\ell} i k \xi_{\ell+1,k} + a_{\ell-1} i k \xi_{\ell-1,k} + \frac{1}{\epsilon} \xi_{\ell,k} = 0, & 1 \leq \ell \leq N-1; \\ \epsilon \partial_t \xi_{N,k} + a_{N-1} i k \xi_{N-1,k} + \frac{1}{\epsilon} \xi_{N,k} = -a_N i k f_{N+1,k}, & \ell = N. \end{cases}$$

$$\partial_t \left( H_0^k(\xi) + h_{\gamma}^k(\xi) \right) \leq -\frac{1}{\epsilon^2} H_3^k(\xi) - \sum_{\ell=0}^2 c_{\gamma,\ell} |\xi_{\ell,k}|^2 + \frac{k^2}{6} |f_{N+1,k}|^2,$$

(i) **High frequency:**  $H_0^k(\xi)(t) \leq 6t H_0^k(\partial_x g) e^{-\frac{2\lambda_1 t}{\epsilon^2}}$

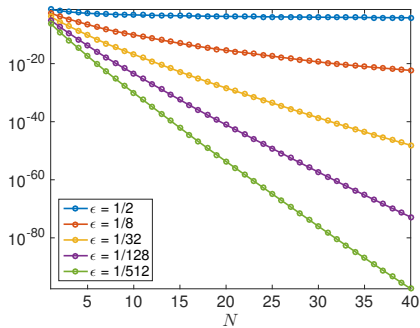
(ii) **Low frequency:**  $H_0^k(\xi)(t) \leq \frac{t}{2} [C_{N+1}^k]^2 k^{2(N+2)} e^{-2\lambda_2 k^2 t} \epsilon^{2(N+1)}$

## Lemma

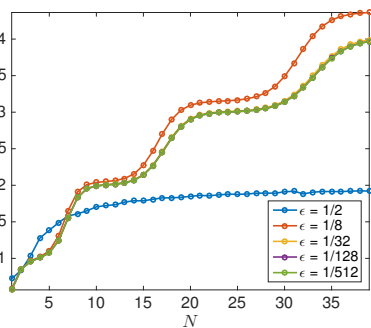
Given isotropic initial condition  $g \in H^1(dx)$ ,

$$\|\xi\|_{L^2(d\mu dx)}(t) \leq C(\partial_x g) \sqrt{t} e^{-\frac{\lambda_1 t}{\epsilon^2}} + \frac{\sqrt{t}}{A} C(g, N+2, t) \epsilon^{N+1}.$$

# Benefits of increasing N: $\|e^N\|_{L^2(d\mu dx)}$



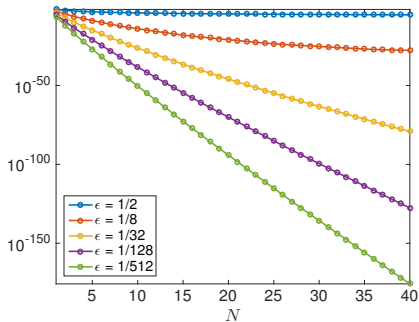
(a)  $\|e^N\|$ , in logarithm scale



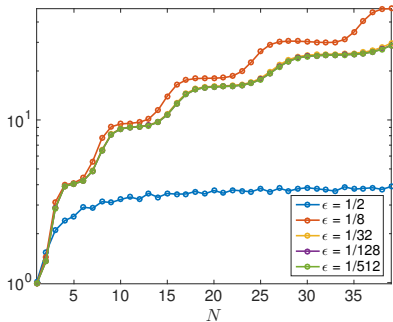
(b)  $\frac{\|e^{N+1}\|}{\|e^N\|_\epsilon}$

Errors of  $P_N$  equations,  $N = 1, \dots, 40$ .

# Benefits of increasing N: $\|\xi_0^N\|_{L^2(dx)}$



(a)  $\|\xi_0^N\|$ , in logarithm scale

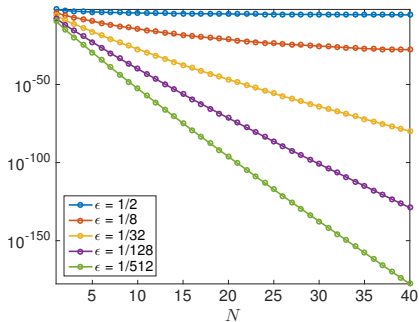


(b)  $\frac{\|\xi_0^{N+1}\|}{\|\xi_0^N\| \epsilon^2}$

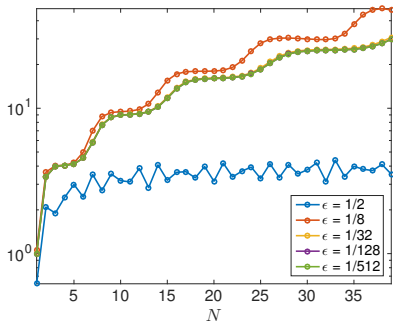
Errors of  $f_0^N$  of  $P_N$  equations,  $N = 1, \dots, 40$ .



# Benefits of increasing N: $\|\xi_1^N\|_{L^2(dx)}$



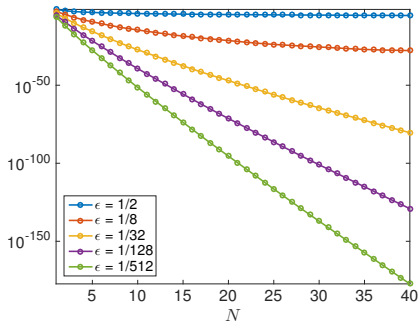
(a)  $\|\xi_1^N\|$ , in logarithm scale



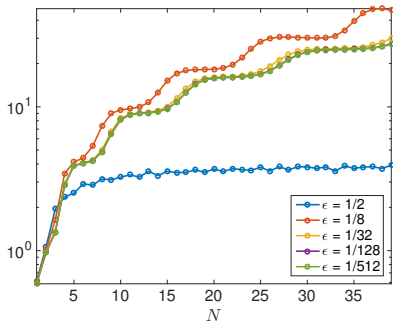
(b)  $\frac{\|\xi_1^{N+1}\|}{\|\xi_1^N\| \epsilon^2}$

Errors of  $f_1^N$  of  $P_N$  equations,  $N = 1, \dots, 40$ .

# Benefits of increasing N: $\|\xi_2^N\|_{L^2(dx)}$



(a)  $\|\xi_2^N\|$ , in logarithm scale



(b)  $\frac{\|\xi_2^{N+1}\|}{\|\xi_2^N\| \epsilon^2}$

Errors of  $f_2^N$  of  $P_N$  equations,  $N = 1, \dots, 40$ .